

Monday, November 30, 2009

Pavan Vempaty a Doctoral Student, won the Best Student Paper Award of International Conference on Modeling...

The following paper, co-authored by Pavan Vempaty, a doctoral student in the ECE Department, and two ECE faculty, Dr. Cheok and Dr. Loh, was awarded "Best Student Paper Award of International Conference on Modeling, Simulation and Control 2009".

Pavan K. Vempaty, Ka C. Cheok, and Robert N. K. Loh, "Model Reference Adaptive Control for Actuators of a Biped Robot Locomotion," Proceedings of the World Congress on Engineering and Computer Science, vol II, pp 983-988, San Francisco, USA, Oct 20-22, 2009. ([Full Text](#))

For more details about the paper, please contact Pavan Vempaty (pvempaty@oakland.edu) .

SUMMARY

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